FUNCTIONAL DIFFERENTIAL EQUATIONS BY SPLINE FUNCTIONS

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1. Introduction

In this paper we present a new method for the approximate solution of functional differential equations. The method is based on third-order spline functions. Suppose that a partition is given on an interval on which we are to solve a first order system of functional differential equations. At the knots we construct approximate values of the solution successively in the following way: the next value is obtained by substituting a third order spline function into the right side of the equation, which takes the previous approximate values at the previous knots, and then integrating it on the next interval. We prove convergence theorems concerning our method and the stability is also established.

Our method can be applied in very general situations whenever the existence and uniqueness of the solution is assured. Namely, we impose a Lipschitz condition on the right side and the continuity of the given functions is assumed.

As we have simple recursive formulae for the approximate values, our method can easily be programmed and the computations can be implemented on small calculators. We illustrate the method by a numerical example. We proceeded the calculations by an electronic calculator TI-59.

Concerning other numerical methods for solving functional differential equations based on spline functions see [1].

Throughout this paper **R** denotes the set of real numbers. If B is a Banach-space and $x:[a,b]\rightarrow B$ continuous or continuously differentiable function, then $\omega(h,x)$ and $\omega_1(h,x)$ denotes the modulus of continuity of x and x', respectively.

2. Construction of the spline function

Let $[a, b] \subset \mathbb{R}$ be an interval and B a Banach-space. Fix a subdivision $a = t_0 < t_1 < \ldots < t_N = b$ of [a, b] and let $h_K = t_K - t_{K-1}$ $(K = 1, \ldots, N)$,

further $h = \max_{1 \le K \le N} h_K$, $\mu = h/\min_{1 \le K \le N} h_K$. If $x : [a, b] \to B$ is a continuously differentiable function, then we denote $x_K = x$ (t_K) (K = 0, 1, ..., N).

Define the spline function S on [a, b] as follows:

(1)
$$S(t) = S_K(t) \quad (t_{K-1} \le t \le t_K),$$

where

$$S_1(t) = x_1 + \frac{1}{h_1} (x_1 - x_0) (t - t_1)$$

and for K = 2, ..., N

$$S_K(t) = x_K + \frac{1}{h_K} (x_K - x_{K-1}) (t - t_K) - \frac{1}{h_K} \left[\frac{1}{h_K} (x_K - x_{K-1}) - \frac{1}{h_{K-1}} (x_{K-1} - x_{K-2}) \right] \left[(t - t_K)^2 + \frac{1}{h_K} (t - t_K)^3 \right].$$

It is obvious that S is continuously differentiable on [a, b].

THEOREM 2.1. For the spline function S defined by (1) we have for all t in [a, b]:

$$||x(t) - S(t)|| \le 6h \omega_1(h, x),$$

 $||x'(t) - S'(t)|| \le 12 \omega_1(h, x).$ [X]

Proof. Let $t_{K-1} \le t \le t_K$ (K = 1, ..., N), then

$$x(t) = x_K + x'(\tau_K) (t - t_K),$$

where $t < \tau_K < t_K$, further let

$$x_K^*(t) = x_K + x_K'(t - t_K),$$

where $x'_{K} = x'(t_{K})$. Then using the Lagrange theorem, we have

$$||x(t) - S(t)|| \leq ||x(t) - x_K^*(t)|| + ||x_K^*(t) - S(t)|| \leq ||x'(\tau_K) - x_K'|| h_K +$$

$$+ \left||x_K' - \frac{1}{h_K} (x_K - x_{K-1})|| h_K + 2h_K \left| \frac{1}{h_K} (x_K - x_{K-1}) - \frac{1}{h_{K-1}} (x_{K-1} - x_{K-2}) \right|| \leq 6h \omega_1(h, x),$$

and

$$||x'(t) - S'(t)|| \le ||x'(t) - x'_{K}|| + ||x'_{K} - S'(t)|| \le ||x'(t) - x'_{K}|| +$$

$$+ ||x'_{K} - \frac{1}{h_{K}} (x_{K} - x_{K-1})|| + 5 ||\frac{1}{h_{K}} (x_{K} - x_{K-1}) - \frac{1}{h_{K-1}} (x_{K-1} - x_{K-2})|| \le$$

$$\le 12\omega_{1}(h, x) . \quad \boxed{\times}$$

THEOREM 2.2. Let x_K , \tilde{x}_K in B be given and $||x_K - \tilde{x}_K|| \le \varepsilon$ (K = 0, 1, ..., N). Let S and \tilde{S} denote the spline function of the form (1) with the values x_K , \tilde{x}_K . Then we have for all t in [a, b]:

$$||S(t) - \tilde{S}(t)|| \le (7 + 4\mu) \varepsilon,$$

$$||S'(t) - \tilde{S}'(t)|| \le 22 \frac{\mu}{h} \varepsilon. \quad [\times]$$

Proof. Let
$$t_{K-1} \le t \le t_K$$
 $(K = 1, ..., N)$, then
$$\|S(t) - \tilde{S}(t)\| = \|S_K(t) - \tilde{S}_K(t)\| \le \|x_K - \tilde{x}_K\| + \|(x_K - x_{K-1}) - (\tilde{x}_K - \tilde{x}_{K-1})\| + 2\|(x_K - x_{K-1}) - (\tilde{x}_K - \tilde{x}_{K-1})\| + 2\frac{h_K}{h_{K-1}} \|(x_{K-1} - x_{K-2}) - (\tilde{x}_{K-1} - \tilde{x}_{K-2})\| \le (7 + 4\mu) \varepsilon ,$$

and

$$||S'(t) - \tilde{S}'(t)|| = ||S'_{K}(t) - \tilde{S}'_{K}(t)|| \le \frac{1}{h_{K}} ||(x_{K} - x_{K-1}) - (\tilde{x}_{K} - \tilde{x}_{K-1})|| + \frac{5}{h_{K}} ||(x_{K} - x_{K-1}) - (\tilde{x}_{K} - \tilde{x}_{K-1})|| + \frac{5}{h_{K-1}} ||(x_{K-1} - x_{K-2}) - (\tilde{x}_{K-1} - \tilde{x}_{K-2})|| \le \frac{22}{h} \varepsilon \cdot |\underline{\times}|$$

REMARK 2.3. In case of equidistant partition we have $\mu = 1$ and the last theorem gives the estimates

$$||S(t) - \tilde{S}(t)|| \le 11 \varepsilon,$$

$$||S'(t) - \tilde{S}'(t)|| \le 22 \frac{\varepsilon}{h}. \quad \boxed{\times}$$

3. Approximate solution of functional differential equations

Let t_0 be a real number, $0 < \gamma < \delta$, further let B be a Banach-space, and $\Theta: [t_0 - \delta, t_0] \to B$, $f: [t_0, \infty) \times B^{n+1} \to B$, $r_i: [t_0, \infty) \to [\gamma, \delta]$ $(i = 1, \ldots, n)$ be continuous functions where f satisfies the Lipschitz condition

$$||f(t, y_1, \ldots, y_{n+1}) - f(t, \overline{y}_1, \ldots, \overline{y}_{n+1})|| \le L \sum_{j=1}^{n+1} ||y_j - \overline{y}_j||,$$

whenever $t \ge t_0$ and y_j , \overline{y}_j are in B (j = 1, ..., n+1).

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Suppose that the function $x:[t_0-\delta, \infty)\to B$ satisfies the system of equations

(2)
$$x'(t) = f(t, x(t), x(t-r_1(t)), \dots, x(t-r_n(t))) \quad (t \ge t_0),$$

$$x(t) = \Theta(t) \quad (t_0 - \delta \le t \le t_0).$$

For $T > t_0$ let us consider the partition

$$t_0 - \delta = t_{-M} < t_{-M+1} < \dots < t_{-1} < t_0 < t_1 < \dots < t_N = T$$

of $[t_0-\delta,T]$, where $t_K-t_{K-1}=h_K<\gamma$ $(K=-M+1,\ldots,N)$. Denote S the spline function of the form (1) with the values $x_K=x$ (t_K) . Then S is an approximate solution of (2). For if $t_0-\delta \le t \le t_0$, then

$$||S(t) - \Theta(t)|| = ||S(t) - x(t)|| \le 6h \omega_1(h, x)$$
,

and if $t \ge t_0$, then

$$||S'(t) - f(t, S(t), S(t - r_1(t)), \dots, S(t - r_n(t)))|| \le$$

$$\le ||S'(t) - x'(t)|| + ||f(t, x(t), x(t - r_1(t)), \dots, x(t - r_n(t))) - f(t, S(t), S(t - r_1(t)), \dots, S(t - r_n(t)))|| \le$$

$$\le 12\omega_1(h, x) + L \sum_{j=0}^{n} ||x(t - r_j(t)) - S(t - r_j(t))|| \le$$

$$\le 12\omega_1(h, x) + 6L(n + 1) h \omega_1(h, x),$$

where $r_0(t) \equiv 0$. Notice, that we know the values x_K only for $K \leq 0$, hence we cannot compute the coefficients of S.

In the next step we construct the approximate values $\tilde{\mathbf{x}}_K$ (K = -M, -M+1, ..., N) and we show that the spline function $\tilde{\mathbf{S}}$ with these values is an approximate solution of (2) and provides a good approximation for \mathbf{x} .

Let $\tilde{\mathbf{x}}_K = \Theta(t_K)$ for K = -M, -M + I, ..., 0 and

(3)
$$\tilde{x}_{K+1} = \tilde{x}_K + \int_{t_K}^{t_{K+1}} f(t, \tilde{x}_K + \tilde{x}'_K(t - t_K), \tilde{S}_{(K)}(t - r_1(t)), \dots, \tilde{S}_{(K)}(t - r_n(t))) dt$$

for K = 0, 1, ..., N-1, where

$$\tilde{x}_{K}' = f(t_{K}, \tilde{x}_{K}, \tilde{S}_{(K)}(t_{K} - r_{1}(t_{K})), \dots, \tilde{S}_{(K)}(t_{K} - r_{n}(t_{K}))) \quad (K \ge 0),$$

$$\tilde{S}_{(0)}(t) = \Theta(t) \quad (t_{0} - \delta \le t \le t_{0})$$

and $\tilde{S}_{(K)}$ $(K \ge 1)$ denotes the spline function of the form (1) with the values \tilde{x}_j $(j = -M, \ldots, K)$ on the interval $[t_0 - \delta, t_K]$. Using (2) we have

$$x_{K+1} = x(t_{K+1}) = x_K + \int_{t_K}^{t_{K+1}} f(t, x(t), x(t-r_1(t)), \dots, x(t-r_n(t))) dt$$

and by the Lagrange theorem it follows for $t_K \le t \le t_{K+1}$ that $x(t) = x_K + x'(\tau_K)$ ($t-t_K$) where $t_K < \tau_K < t_{K+1}$. Let $S_{(K)}$ denote the spline function of the form (1) with the values x_j ($j = -M, \ldots, K$) on the interval $[t_0 - \delta, t_K]$.

$$||x_{K+1} - \tilde{x}_{K+1}|| \le ||x_K - \tilde{x}_K|| +$$

$$+ \int_{t_K}^{t_{K+1}} ||f(t, x(t), \dots, x(t-r_n(t))) - f(t, \tilde{x}_K + \hat{x}_K'(t-t_K), \dots, \tilde{S}_{(K)}(t-r_n(t)))|| dt \le$$

$$\le ||x_K - \tilde{x}_K|| + L \int_{t_K}^{t_{K+1}} ||x(t) - \tilde{x}_K - \tilde{x}_K'(t-t_K)|| dt +$$

$$+ L \int_{j=1}^{n} \int_{t_K}^{t_{K+1}} ||x(t-r_j(t)) - \tilde{S}_{(K)}(t-r_j(t))|| \le ||x_K - \tilde{x}_K|| +$$

$$+ L \int_{t_K}^{t_{K+1}} ||x_K - \tilde{x}_K|| + ||x'(\tau_K) - x'(t_K)|| (t-t_K) + ||x'(t_K) - \tilde{x}_K'|| (t-t_K)|| dt +$$

$$+ L \sum_{j=1}^{n} \int_{t_K}^{t_{K+1}} ||x(t-r_j(t)) - S_{(K)}(t-r_j(t))|| + ||S_{(K)}(t-r_j(t)) - \tilde{S}_{(K)}(t-r_j(t))|| dt .$$
Now let

$$\delta_K = \max_{0 \le i \le K} \|x_j - \bar{x}_i\|,$$

then

$$||x_{K+1} - \tilde{x}_{K+1}|| \leq ||x_K - \tilde{x}_K|| + L h_{K+1}||x_K - \tilde{x}_K|| + L \frac{h_{K+1}^2}{2} \omega_1(h, x) +$$

$$+ L \frac{h_{K+1}^2}{2} ||f(t_K, x_K, \dots, x(t_K - r_n(t_K))) - f(t_K, \tilde{x}_K, \dots, \tilde{S}_{(K)}(t_K - r_n(t_K)))|| +$$

$$+ 6L h h_{K+1} n \omega_1(h, x) + (7 + 4\mu) L h_{K+1} n \delta_K \leq$$

$$\leq ||x_K - \tilde{x}_K|| (1 + Lh) + \frac{L}{2} h^2 \omega_1(h, x) +$$

$$+ \frac{L^2}{2} h^2 \left[||x_K - \tilde{x}_K|| + \sum_{j=1}^n ||x(t_K - r_j(t_K)) - S_{(K)}(t_K - r_j(t_K))|| +$$

$$+ \sum_{j=1}^n ||S_{(K)}(t_K - r_j(t_K)) - \tilde{S}_{(K)}(t_K - r_j(t_K))|| \right] +$$

$$+ 6L h^2 n \omega_1(h, x) + (7 + 4\mu) L h n \delta_K.$$

This implies

$$||x_{K+1} - \tilde{x}_{K+1}|| \le \delta_K (1 + c_0) + c_1 h^2 \omega_1(h, x)$$

where c_0 and c_1 are constants independent of h. We remark that these constants are dependent on μ . But if we suppose that μ is bounded from above by a constant independent of h, then the latter inequalities give us

$$\delta_{K+1} \leq c_2 \, h \, \, \omega_1(h,x) \, ,$$

where the constant c_2 is independent of h (see e.g. [2]).

THEOREM 3.1. Suppose that the functions in (2) satisfy the above mentioned conditions. Then the spline function \tilde{S} with the values \hat{x}_K $(K=-M,\ldots,$..., N) constructed by (3) has the properties

$$\|x(t) - \tilde{S}(t)\| \leq \text{const. } h \omega_1(h, x)$$

$$\|x'(t) - \tilde{S}'(t)\| \leq \text{const. } \omega_1(h, x)$$

$$\|\tilde{S}'(t) - f(t, \tilde{S}(t), \tilde{S}(t - r_1(t)), \dots, \tilde{S}(t - r_n(t)))\| \leq \text{const. } \omega_1(h, x)$$

for t > 0 and

$$\|\Theta(t) - \tilde{S}(t)\| \le \text{const. } h \omega_1(h, x)$$

for $-\delta \le t \le 0$.

This theorem is an easy consequence of the previous considerations. We remark, that the constants here may depend on the number μ . But if we let $h \to 0$ and μ remains bounded (for instance $\mu = 1$, in case of equidistant partitions), our theorem gives the convergence of \tilde{S} to the exact solution.

4. Application

Now we apply our previous results for the following linear problem

(4)
$$x'(t) = A_0 x(t) + \sum_{j=1}^{n} A_j x(t-j) + c \quad (t > 0)$$

$$x(t) = \Theta(t) \quad (t \le 0)$$

where A_j is a bounded linear operator of the Banach space B(j = 0, 1, ..., n), $\Theta: [-n, 0] \rightarrow B$ is a given function and c is an element of B. In this case we obtain particularly simple recursive equations for the approximate values \tilde{x}_K .

Let T>0 be an integer, $h=\frac{1}{N}$ and $t_K=\frac{K}{N}$ $(K=-Nn, \ldots, NT)$.

By (3) we have

$$\tilde{\chi}_K = \chi_K = \Theta(Kh)$$

for
$$K = -Nn$$
, ..., -1 , 0, and
$$\tilde{x}_1 = \tilde{x}_0'(I + A_0 h) + A_0 \tilde{x}_0' \frac{h^2}{2} + \sum_{j=1}^n A_j \int_{-j}^{-j+h} \Theta(t) dt + \epsilon h,$$

where

$$\tilde{x}_0' = \sum_{j=0}^n A_j \Theta(-j) + c$$

(I denotes the identity operator). Further, for $k \ge 1$

$$\tilde{x}_{K+1} = \tilde{x}_K + \int_{t_K}^{t_{K+1}} A_0(\tilde{x}_K + \hat{x}_K'(t - t_K)) dt + \sum_{j=1}^n A_j \int_{t_K}^{t_{K+1}} \tilde{S}_{(K)}(t - j) dt + ch,$$

where

$$\tilde{x}'_{K} = \sum_{j=0}^{n} A_{j} \tilde{x}_{K-jN} + c.$$

On the other hand, an easy computation gives

$$\int_{t_K}^{t_{K+1}} \tilde{S}_{(K)}(t-j) dt = \int_{t_{K-jN}}^{t_{K+1-jN}} \tilde{S}_{(K)}(t) dt =$$

$$= h \left[\frac{5}{12} \tilde{x}_{K+1-jN} + \frac{2}{3} \tilde{x}_{K-jN} - \frac{1}{12} \tilde{x}_{K+1-jN} \right].$$

Finally, we have the following recursive formulae for the problem (4):

$$\tilde{x}_{K} = \Theta(Kh) \quad (K = -Nn, ..., -1, 0),$$

$$\tilde{x}_{1} = (I + A_{0}h)\tilde{x}_{0} + \frac{h^{2}}{2} \sum_{j=0}^{n} A_{0} A_{j} \Theta(-j) + \frac{h^{2}}{2} A_{0} c + hc + \sum_{j=1}^{n} A_{j} \int_{-j}^{-j+h} \Theta(t) dt,$$

$$\tilde{x}_{K+1} = \left(I + A_{0}h + A_{0}^{2} \frac{h^{2}}{2}\right) \tilde{x}_{K} + \frac{h^{2}}{2} \left(\sum_{j=1}^{n} A_{0} A_{j} \tilde{x}_{K-jN} + A_{0} c\right) +$$

$$+ hc + h \sum_{j=1}^{n} A_{j} \left[\frac{5}{12} \tilde{x}_{K+1-jN} + \frac{2}{3} \tilde{x}_{K-jN} - \frac{1}{12} \tilde{x}_{K-1-jN}\right] (K=1, 2, ..., NT).$$

5. Example

Here we consider the example

$$x'(t) = 5x(t) + x(t-1)$$
 $(t>0)$

$$x(t) = 5 \qquad (-1 \le t \le 0)$$

(see [1]). The exact solution on [0, 1] is

$$x(t) = 6e^{5t} - 1$$

and on [1, 2] is

1.9

$$x(t) = \left[x(1) - \frac{1}{5} + 6(t-1)\right] e^{5(t-1)} + \frac{1}{5}.$$

Using N=900 we obtain the results summarized in the following tible:

-			Table
1	x(t)	Š(t)	x(t) - \$2.
0. 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1.0 1.1 1.2 1.3 1.4 1.5 1.6 1.7 1.8	5. 8.892327624 15.30969097 25.89013442 43.33433659 72.09496376 119.5132215 197.6927118 326.5889002 539.1027878 889.4789546 1467.362361 2420.772761 3993.738812 6588.865818 10870.38298 17934.15321 29588.1594 48815.2569	5. 8.892302286 15.30960742 25.88992779 43.33388236 72.09402765 119.5113695 197.6891493 326.5821876 539.0903372 889.4561617 1467.326525 2420.730253 3993.673437 6588.765777 10870.23076 17933.92318 29587.81453 48814.74486 80535.88165	0. 0,00025338 0,000025338 0,00029653 0,00029653 0,00093611 0,001852 0,0035625 0,0067126 0,0124506 0,0227929 0,035836 0,042508 0,065375 0,100041 0,15222 0,23003 0,34487 0,51204 0,75128

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